

EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L2	20	318/600-610.ccls. and position adj controller and (PI or PID)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/06/20 14:59
L3	35	318/600-632.ccls. and position adj controller and (PI or PID)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/06/20 15:04
L4	272	318/600-632.ccls. and position adj control and (PI or PID)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/06/20 15:14
L5	14	("3998409" "4540923" "4862343" "5157597" "5216342" "5263113" "5304906" "5444341").PN. OR ("5691615").URPN.	US-PGPUB; USPAT; USOCR	OR	OFF	2006/06/20 15:10
L6	39	318/600-632.ccls. and position adj control and (PI or PID) and low adj pass and filter	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/06/20 15:26
L7	630	318/560-632.ccls. and position and (speed or velocity) and torque and (PI or PID)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/06/20 15:27
L8	307	318/560-632.ccls. and position and (speed or velocity) and torque and (PI or PID) and (filter or compensation)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/06/20 15:28
L9	76	318/432-434.ccls. and position and (speed or velocity) and torque and (PI or PID) and (filter or compensation)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/06/20 15:28

EAST Search History

L10	228	318/700-800.ccls. and position and (speed or velocity) and torque and (PI or PID) and (filter or compensation)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/06/20 15:28
L11	210	position and (speed or velocity) adj controller and torque	EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/06/20 15:28
L12	4	"6869272"	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/06/20 15:28
L13	10	"6555988"	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/06/20 15:29
L14	353	318/600-632.ccls. and position and (speed or velocity) and torque and (PI or PID)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/06/20 15:29
L15	48	position and (speed or velocity) and torque and (PI or PID) and controller	EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/06/20 15:30